

GEOMETRY: EXAMPLES 1

1. Given a real constant c , let $\Sigma = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 - z^2 = c\}$.
 - (a) Sketch Σ for a representative selection of values of c .
 - (b) For which values is Σ an embedded surface in \mathbb{R}^3 ? Justify your answer.
 - (c) Write down parametrisations covering Σ in the cases where it is an embedded surface.
2. Show that a subset $\Sigma \subset \mathbb{R}^3$ is an embedded surface iff for all p in Σ there exists an open neighbourhood T of p in \mathbb{R}^3 , an open neighbourhood W of the origin in \mathbb{R}^3 , and a diffeomorphism $g : T \rightarrow W$ such that $g(T \cap \Sigma) = W \cap (\mathbb{R}^2 \times \{0\})$.
3. Show that the map $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by

$$\sigma(u, v) = \left(\frac{u}{1 + u^4}, v, \frac{u^2}{1 + u^4} \right)$$

is smooth, that it is a bijection onto its image Σ , and that $D_q\sigma$ is injective for all $q \in \mathbb{R}^2$. Sketch Σ and show that it is not an embedded surface.

4. Consider the polar and Cartesian parametrisations $\sigma(r, \theta) = (r \cos \theta, r \sin \theta)$ and $\tau(x, y) = (x, y)$ of \mathbb{R}^2 near $p \neq 0$.
 - (a) Sketch the vectors $\sigma_r, \sigma_\theta, \tau_x,$ and τ_y at a selection of points.
 - (b) Using the the change of basis formula from lectures, express τ_x and τ_y in terms of σ_r and σ_θ . [Hint: use the chain rule to avoid expressing r and θ in terms of x and y .]
 - (c) Verify your answer using explicit expressions for σ_r and σ_θ .
5. Let $F : \Sigma_1 \rightarrow \Sigma_2$ be a smooth map between embedded surfaces. Given $p \in \Sigma_1$ define a map

$$D_p F : T_p \Sigma_1 \rightarrow T_{F(p)} \Sigma_2$$

as follows. Pick parametrisations σ_1 of Σ_1 near p and σ_2 of Σ_2 near $F(p)$ with WLOG $\sigma_1(0) = p$ and $\sigma_2(0) = F(p)$. Note that $D_0\sigma_1$ gives a linear isomorphism $\mathbb{R}^2 \rightarrow T_p \Sigma_1$. Define

$$D_p F = D_0\sigma_2 \circ D_0(\sigma_2^{-1} \circ F \circ \sigma_1) \circ (D_0\sigma_1)^{-1}.$$

- (a) Show that this is independent of the choices of σ_1 and σ_2 .
- (b) Show that if $v \in T_p \Sigma_1$ is given by $\dot{\gamma}(0)$, for a smooth map $\gamma : (-\varepsilon, \varepsilon) \rightarrow \mathbb{R}^3$ with image contained in Σ_1 and with $\gamma(0) = p$, then $D_p F(v) = (F \circ \gamma)'(0)$. [Hint: Write γ in the form $\sigma_1 \circ \Gamma$.]
6. Let $\sigma^\pm : \mathbb{R}^2 \rightarrow S^2$ be the inverse stereographic projection parametrisations, given by

$$\sigma^\pm(u, v) = \frac{1}{u^2 + v^2 + 1} (2u, 2v, \pm(u^2 + v^2 - 1)).$$

Identify \mathbb{R}^2 with \mathbb{C} and let $P : \mathbb{C} \rightarrow \mathbb{C}$ be a non constant complex polynomial. Define $F : S^2 \rightarrow S^2$ by

$$F(p) = \begin{cases} \sigma^+ \circ P \circ (\sigma^+)^{-1}(p) & \text{if } p \in S^2 \setminus \{(0, 0, 1)\} \\ (0, 0, 1) & \text{if } p = (0, 0, 1). \end{cases}$$

- (a) Show that F is smooth.
- (b) For $P(\zeta) = \zeta^3 + \zeta^2 + 1$, at which points is F a local diffeomorphism?
7. Show that the Möbius band, defined to be the image of the map $\sigma : (-1, 1) \times \mathbb{R} \rightarrow \mathbb{R}^3$ given by

$$\sigma(u, v) = ((2 + u \cos \frac{v}{2}) \cos v, (2 + u \cos \frac{v}{2}) \sin v, u \sin \frac{v}{2}),$$
 is not orientable. [Hint: Take Gauss maps n_1 and n_2 defined where $v \in (-\pi, \pi)$ and $v \in (0, 2\pi)$ respectively, and compare a putative global Gauss map n with them.]
8. Suppose that Σ is an embedded surface defined by the vanishing of single function, i.e. that $\Sigma = f^{-1}(0)$ where f is a smooth function on an open subset of \mathbb{R}^3 satisfying $D_p f \neq 0$ for all $p \in \Sigma$. Show that Σ is orientable, and deduce that there exist embedded surfaces that cannot be defined by the vanishing of a single function.